LAMPIRAN

Lampiran 1 Coding

```
#Libraries
import RPi.GPIO as GPIO
import time

#GPIO Mode (BOARD / BCM)
GPIO.setmode (GPIO.BCM)

#set GPIO Pins
GPIO_TRIGGER = 18
GPIO_ECHO = 24

#set GPIO direction (IN / OUT)
GPIO.setup(GPIO_TRIGGER, GPIO.OUT)
GPIO.setup()GPIO_ECHO, GPIO.IN

def distance():
        # set Trigger to HIGH
        GPIO.output(GPIO_TRIGGER, True)

        #set Trigger after 0.01ms to LOW
        Time.sleep(0.00001)
        GPIO.Output(GPIO_TRIGGER, False)

        StartTime = time.time()
        StopTime = time.time()

        # save StartTime
        while GPIO.input(GPIO_ECHO) == 0:
                StartTime = time.time()

        # save time of arrival
        while GPIO.input(GPIO_ECHO) == 1:
                StopTime = time.time()

        # time difference between start and arrival
        TimeElapsed = StopTime – StartTime
        # multiply with the sonic speed (34300) / 2
        # and divide by 2, because there and back
        distance = (Timelapsed * 34300) / 2

        return distance
```

```
        # time difference between start and arrival
        TimeElapsed = StopTime – StartTime
        # multiply with the sonic speed (34300 cm/s)
        # and divide by 2, because there and back
        distance = (TimeElapsed * 34300) / 2

        return distance
if _ _name__ == '_ _main_ _':
        try:
                while True:
                        dist = distance()
                        print ("Measured Distance = %.1f cm" % dist)
                        time.sleep(1)
                # Reset by pressing CTRL + C
        except KeyboardInterrupt:
                print("Measurement stopped by User")
                GPIO.cleanup()
```

Lampiran 2 Datasheet Raspberry Pi B+

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RASPBERRY PI 3 MODEL B

Product Name: RASPBERRYPI3-MODB-1GB

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Technical Specification:

Processor

- Broadcom BCM2387 chipset.
- 1.2GHz Quad-Core ARM Cortex-A53 (64Bit)

802.11 b/g/n Wireless LAN and Bluetooth 4.1 (Bluetooth Classic and LE)

- IEEE 802.11 b / g / n Wi-Fi. Protocol: WEP, WPA WPA2, algorithms AES-CCMP (maximum key length of 256 bits), the maximum range of 100 meters.
- IEEE 802.15 Bluetooth, symmetric encryption algorithm Advanced Encryption Standard (AES) with 128-bit key, the maximum range of 50 meters.

GPU

- Dual Core Video Core IV® Multimedia Co-Processor. Provides Open GL ES 2.0, hardware-accelerated Open VG, and 1080p30 H.264 high-profile decode.
- Capable of 1Gpixel/s, 1.5Gtexel/s or 24GFLOPs with texture filtering and DMA infrastructure

Memory

- 1GB LPDDR2

Operating System

- Boots from Micro SD card, running a version of the Linux operating system or Windows 10 IoT

Dimensions

- 85 x 56 x 17mm

Power

- Micro USB socket 5V1, 2.5A

Connectors:

Ethernet

- 10/100 BaseT Ethernet socket

Video Output

- HDMI (rev 1.3 & 1.4)
- Composite RCA (PAL and NTSC)

Audio Output

- Audio Output 3.5mm jack
- HDMI
- USB 4 x USB 2.0 Connector

GPIO Connector

- 40-pin 2.54 mm (100 mil) expansion header: 2x20 strip
- Providing 27 GPIO pins as well as +3.3 V, +5 V and GND supply lines

Camera Connector

- 15-pin MIPI Camera Serial Interface (CSI-2)

Display Connector

- Display Serial Interface (DSI) 15 way flat flex cable connector with two data lanes and a clock lane

Memory Card Slot

- Push/pull Micro SDIO

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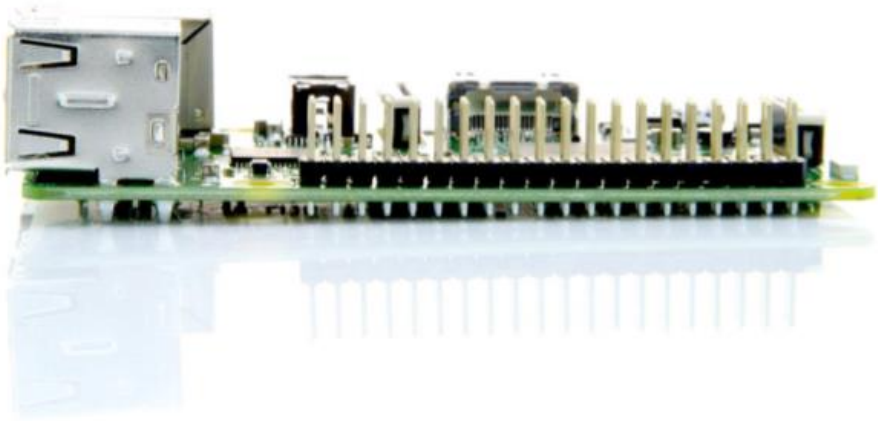
The GPU provides Open GL ES 2.0, hardware-accelerated Open VG, and 1080p30 H.264 high-profile decode and is capable of 1Gpixel/s, 1.5Gtexel/s or 24 GFLOPs of general purpose compute. What's that all mean? It means that if you plug the Raspberry Pi 3 into your HDTV, you could watch BluRay quality video, using H.264 at 40MBits/s

The biggest change that has been enacted with the Raspberry Pi 3 is an upgrade to a next generation main processor and improved connectivity with Bluetooth Low Energy (BLE) and BCM43143 Wi-Fi on board. Additionally, the Raspberry Pi 3 has improved power management, with an upgraded switched power source up to 2.5 Amps, to support more powerful external USB devices.



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The Raspberry Pi 3's four built-in USB ports provide enough connectivity for a mouse, keyboard, or anything else that you feel the RPi needs, but if you want to add even more you can still use a USB hub. Keep in mind, it is recommended that you use a powered hub so as not to overtax the on-board voltage regulator. Powering the Raspberry Pi 3 is easy, just plug any USB power supply into the micro-USB port. There's no power button so the Pi will begin to boot as soon as power is applied, to turn it off simply remove power. The four built-in USB ports can even output up to 1.2A enabling you to connect more power hungry USB devices (This does require a 2Amp micro USB Power Supply)

On top of all that, the low-level peripherals on the Pi make it great for hardware hacking. The 0.1" spaced 40-pin GPIO header on the Pi gives you access to 27 GPIO, UART, I²C, SPI as well as 3.3 and 5V sources. Each pin on the GPIO header is identical to its predecessor the Model B+.

SoC

Built specifically for the new Pi 3, the Broadcom BCM2837 system-on-chip (SoC) includes four high-performance ARM Cortex-A53 processing cores running at 1.2GHz with 32kB Level 1 and 512kB Level 2 cache memory, a VideoCore IV graphics processor, and is linked to a 1GB LPDDR2 memory module on the rear of the board.

GPIO

The Raspberry Pi 3 features the same 40-pin general-purpose input-output (GPIO) header as all the Pis going back to the Model B+ and Model A+. Any existing GPIO hardware will work without modification; the only change is a switch to which UART is exposed on the GPIO's pins, but that's handled internally by the operating system.

USB chip

The Raspberry Pi 3 shares the same SMSC LAN9514 chip as its predecessor, the Raspberry Pi 2, adding 10/100 Ethernet connectivity and four USB channels to the board. As before, the SMSC chip connects to the SoC via a single USB channel, acting as a USB-to-Ethernet adaptor and USB hub.

Antenna

There's no need to connect an external antenna to the Raspberry Pi 3. Its radios are connected to this chip antenna soldered directly to the board, in order to keep the size of the device to a minimum. Despite its diminutive stature, this antenna should be more than capable of picking up wireless LAN and Bluetooth signals – even through walls.

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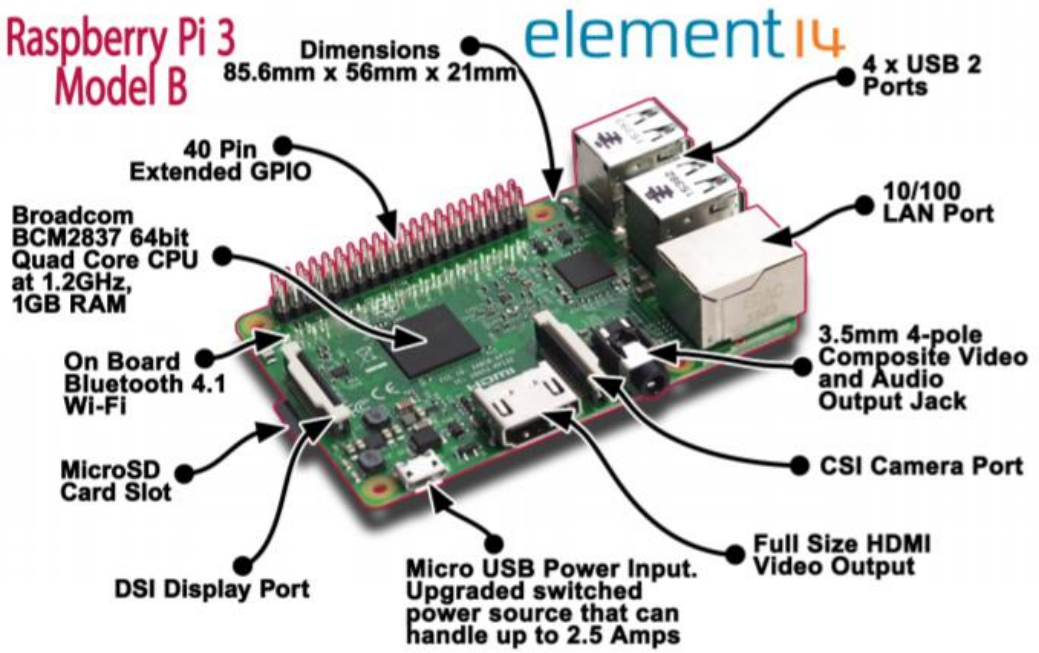

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Key Improvements from Pi 2 Model B to Pi 3 Model B:

- Next Generation QUAD Core Broadcom BCM2837 64bit ARMv7 processor
- Processor speed has increased from 900MHz on Pi 2 to 1.25Ghz on the RPi 3 Model B
- BCM43143 Wi-Fi on board
- Bluetooth Low Energy (BLE) on board
- Upgraded switched power source up to 2.5 Amps (can now power even more powerful devices over USB ports)

The main differences are the quad core 64-bit CPU and on-board Wi-Fi and Bluetooth. The RAM remains 1GB and there is no change to the USB or Ethernet ports. However, the upgraded power management should mean the Pi 3 can make use of more power hungry USB devices

For Raspberry Pi 3, Broadcom have supported us with a new SoC, BCM2837. This retains the same basic architecture as its predecessors BCM2835 and BCM2836, so all those projects and tutorials which rely on the precise details of the Raspberry Pi hardware will continue to work. The 900MHz 32-bit quad-core ARM Cortex-A7 CPU complex has been replaced by a custom-hardened 1.2GHz 64-bit quad-core ARM Cortex-A53

In terms of size it is identical to the B+ and Pi 2. All the connectors and mounting holes are in the same place so all existing add-ons, HATs and cases should fit just fine although the power and activity LEDs have moved to make room for the WiFi antenna.

The performance of the Pi 3 is roughly 50-60% faster than the Pi 2 which means it is ten times faster than the original Pi.

All of the connectors are in the same place and have the same functionality, and the board can still be run from a 5V micro-USB power adapter. This time round, we're recommending a 2.5A adapter if you want to connect power-hungry USB devices to the Raspberry Pi.

Raspberry Pi 3 Model B

Raspberry Pi 2 Model B

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	Raspberry Pi 3 Model B	Raspberry Pi 2 Model B	Model B+	Model A+	Model A	CMDK
Processor Chipset	Broadcom BCM2837 64Bit ARMv7 Quad Core Processor powered Single Board Computer running at 1250MHz	Broadcom BCM2836 32bit ARMv7 Quad Core Processor powered Single Board Computer running at 900MHz	Broadcom BCM2835 32bit ARMv6 SoC full HD multimedia applications processor	Broadcom BCM2835 32bit ARMv6 SoC full HD multimedia applications processor	Broadcom BCM2835 32bit ARMv6 SoC full HD multimedia applications processor	Broadcom BCM2835 32bit ARMv6 SoC full HD multimedia applications processor
GPU	Videocore IV	Videocore IV	Videocore IV	Videocore IV	Videocore IV	Videocore IV
Processor Speed	QUAD Core @1250 MHz	QUAD Core @900 MHz	Single Core @700 MHz	Single Core @700 MHz	Single Core @700 MHz	Single Core @700 MHz
RAM	1GB SDRAM @ 400 MHz	1GB SDRAM @ 400 MHz	512 MB SDRAM @ 400 MHz	256 MB SDRAM @ 400 MHz	256 MB SDRAM @ 400 MHz	512 MB SDRAM @ 400 MHz
Storage	MicroSD	MicroSD	MicroSD	MicroSD	SDCard	4GB eMMC
USB 2.0	4x USB Ports	4x USB Ports	4x USB Ports	1x USB Port	1x USB Port	1x USB Port
Power Draw / voltage	2.5A @ 5V	1.8A @ 5V	1.8A @ 5V	1.8A @ 5V	1.2A @ 5V	1.8A @ 5V
GPIO	40 pin	40 pin	40 pin	40 pin	26 pin	120 pin
Ethernet Port	Yes	Yes	Yes	No	No	No
Wi-Fi	Built in	No	No	No	No	No
Bluetooth LE	Built in	No	No	No	No	No

Lampiran 3 Datasheet Ultrasonic HC-SR04

HC-SR04 User Guide

1. Ultrasonic Distance Measurement Principles

The transmitter emits a 8 bursts of an directional 40KHz ultrasonic wave when triggered and starts a timer. Ultrasonic pulses travel outward until they encounter an object, The object causes the the wave to be reflected back towards the unit. The ultrasonic receiver would detect the reflected wave and stop the stop timer. The velocity of the ultrasonic burst is 340m/sec. in air. Based on the number of counts by the timer, the distance can be calculated between the object and transmitter The TRD Measurement formula is expressed as: D = C X T which is know as the time/rate/distance measurement formula where D is the measured distance, and R is the propagation velocity (Rate) in air (speed of sound) and T represents time. In this application T is devided by 2 as T is double the time value from transmitter to object back to receiver.

2. Product Features

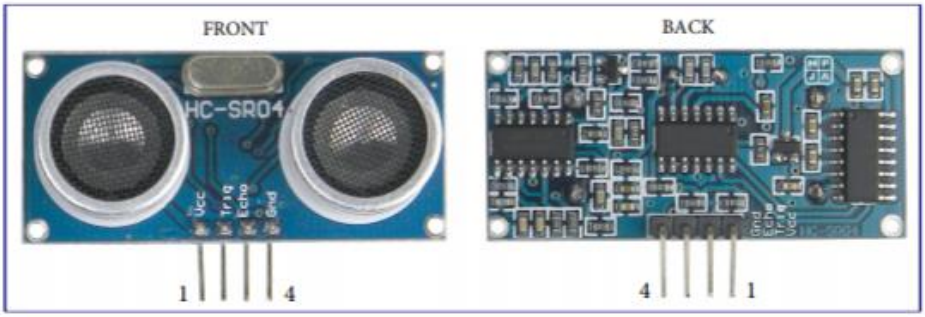
Features

- Stable performance (Xtal.)
- Accurate distance measurement
- High-density SMD Board
- Close Range (2cm)

Uses

- Robotics barrier
- Object distance measurement
- Level detection
- Security systems
- Vehicle detection/avoidance

3. Product Views



4. Module Pin Asignments

	Pin Symbol	Pin Function Description
1	VCC	5V power supply
2	Trig	Trigger Input pin
3	Echo	Receiver Output pin
4	GND	Power ground

5. Electrical Specifications

WARARNING

Do Not connect Module with Power Applied! Always apply power after connecting Connect "GND" Terminal first

Electrical Parameters	HC-SR04 Ultrasonic Module
Operating Voltage	5VDC
Operating Current	15mA
Operating Frequency	40KHz
Max. Range	4m
Nearest Range	2cm
Measuring Angle	15 Degrees
Input Trigger Signal	10us min. TTL pulse
Output Echo Signal	TTL level signal, proportional to distance
Board Dimensions	1-13/16" X 13/16" X 5/8"
Board Connections	4 X 0.1" Pitch Right Angle Header Pins

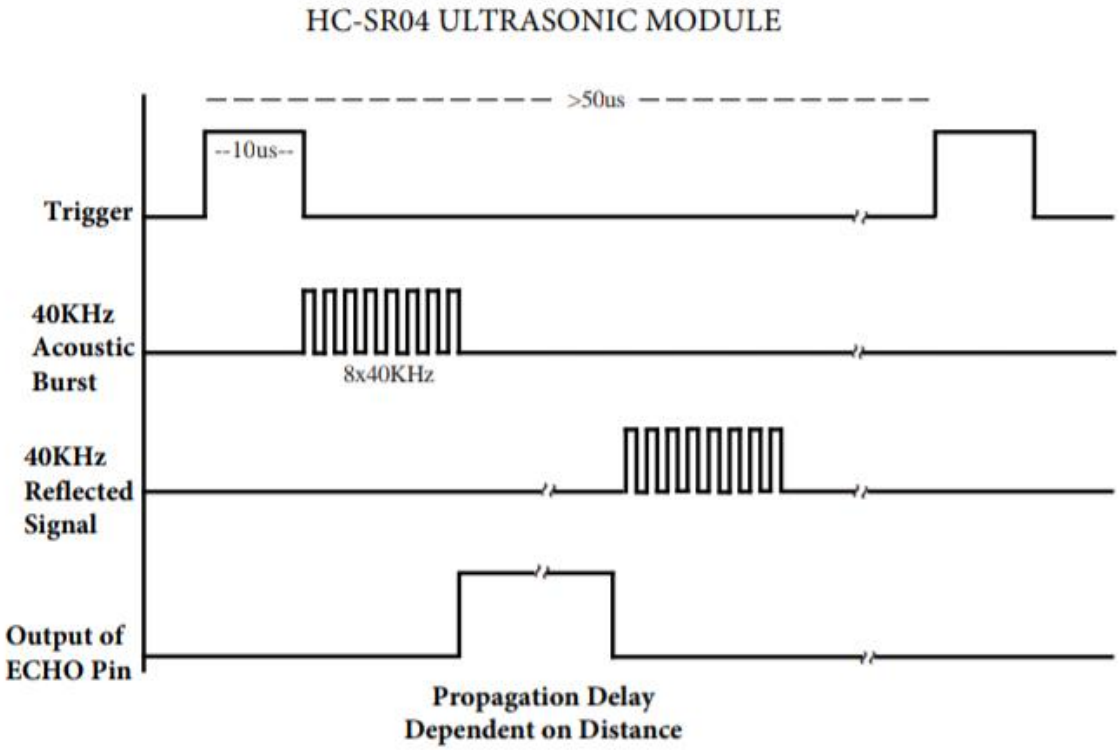
6. Module Operation

Set Trig and Echo Low to initalize module. Place a minimum 10us High level pulse to "Trigger" (module will automatically send eight 40KHz acoustic bursts). At the same time, Gate the microcontroller timer to start timing.

Wait to capture the rising edge output of ECHO port to stop the timer. Now read the time of the counter, which is the ultrasonic propagation time in the air. According to the formula: Distance = (ECHO high level time X ultrasonic velocity (Speed of Sound in air 340m/sec) / 2, you can calculate the distance to the obstacle.

For best results and maximum range, the Object should be larger than 0.5M^2 the nearer the target object, the smaller it may be

7. ModuleTiming



Trigger 10us min. start measurement from microcontroller.
Max Rep. Rate: 50us
ECHO Output pulse to microcontroller, width is the time from last of 8 40KHz bursts to detected reflected signal (microcontroller Timer gate signal)
Distance in cm = echo pulse width in uS/58
Distance in inch = echo pulse width in uS/148

Lampiran 4 Datasheet GPS NEO UBLOK 6-M

NEO-6 series

Versatile u-blox 6 GPS modules

GPS

locate, communicate, accelerate

Highlights

- UART, USB, DDC (I²C compliant) and SPI interfaces
- Available in Crystal and TCXO versions
- Onboard RTC crystal for faster warm and hot starts
- 1.8 V and 3.0 V variants

NEO-6:
12.2 x 16.0 x 2.4 mm

Features

- u-blox 6 position engine:
  - Navigate down to –162 dBm and –148 dBm coldstart
  - Faster acquisition with AssistNow Autonomous
  - Configurable power management
  - Hybrid GPS/SBAS engine (WAAS, EGNOS, MSAS)
  - Anti-jamming technology
- Simple integration with u-blox wireless modules
- A-GPS: AssistNow Online and AssistNow Offline services, OMA SUPL compliant
- Backward compatible (hardware and firmware); easy migration from NEO-5 family or NEO-4S
- LCC package for reliable and cost effective manufacturing
- Compatible with u-blox GPS Solution for Android
- Based on GPS chips qualified according to AEC-Q100
- Manufactured in ISO/TS 16949 certified production sites
- Qualified according to ISO 16750

Product description

The NEO-6 module series brings the high performance of the u-blox 6 position engine to the miniature NEO form factor. u-blox 6 has been designed with low power consumption and low costs in mind. Intelligent power management is a breakthrough for low-power applications. These receivers combine a high level of integration capability with flexible connectivity options in a small package. This makes them perfectly suited for mass-market end products with strict size and cost requirements. The DDC interface provides connectivity and enables synergies with u-blox LEON and LISA wireless modules.

All NEO-6 modules are manufactured in ISO/TS 16949 certified sites. Each module is tested and inspected during production. The modules are qualified according to ISO 16750 - Environmental conditions and electrical testing for electrical and electronic equipment for road vehicles.

Product selector

Model	Type				Supply		Interfaces				Features						
	Standalone GPS	Standalone GLONASS	Timing & Raw Data	Dead Reckoning	1.75 V - 2.0 V	2.7 V - 3.6 V	UART	USB	SPI	DDC (I²C compliant)	Programmable (Flash) FW update	Oscillator	RTC crystal	Antenna supply and supervisor	Configuration pins	Timepulse	External interrupt / Wakeup
NEO-6G	•				•		•	•	•	•		T	•	o	3	1	•
NEO-6Q	•					•	•	•	•	•		T	•	o	3	1	•
NEO-6M	•					•	•	•	•	•		C	•	o	3	1	•

o = requires external components and integration on application processor

C = Crystal / T = TCXO

Receiver performance data

Receiver type	50-channel u-blox 6 engine GPS L1 C/A code SBAS: WAAS, EGNOS, MSAS		
Navigation update rate	up to 5 Hz		
Accuracy[1]	Position SBAS	2.5 m CEP 2.0 m CEP	
Acquisition[1]		NEO-6G/Q	NEO-6M
	Cold starts: Aided starts[2]: Hot starts:	26 s 1 s 1 s	27 s < 3 s 1 s
Sensitivity[3]		NEO-6G/Q	NEO-6M
	Tracking: Cold starts: Hot starts:	−162 dBm −148 dBm −157 dBm	−161 dBm −147 dBm −156 dBm

[1] All SV @ −130 dBm
[2] Dependent on aiding data connection speed and latency
[3] Demonstrated with a good active antenna

Electrical data

Power supply	2.7 V – 3.6 V (NEO-6Q/6M) 1.75 V – 2.0 V (NEO-6G)
Power consumption	111 mW @ 3.0 V (continuous) 33 mW @ 3.0 V Power Save Mode (1 Hz) 68 mW @ 1.8 V (continuous) 22 mW @ 1.8 V Power Save Mode (1 Hz)
Backup power	1.4 V – 3.6 V, 22 µA
Supported antennas	Active and passive

Interfaces

Serial interfaces	1 UART 1 USB V2.0 full speed 12 Mbit/s 1 DDC (I²C compliant) 1 SPI	
Digital I/O	Configurable timepulse 1 EXTINT input for Wakeup	
Serial and I/O	Voltages	2.7 – 3.6 V (NEO-6Q/6M) 1.75 – 2.0 V (NEO-6G)
Timepulse	Configurable	0.25 Hz to 1 kHz
Protocols	NMEA, UBX binary, RTCM	

Specification applies to FW 7

Package

24 pin LCC (Leadless Chip Carrier): 12.2 x 16.0 x 2.4 mm, 1.6 g

Pinout

Environmental data, quality & reliability

Operating temp. −40° C to 85° C

Storage temp. −40° C to 85° C

RoHS compliant (lead-free)

Qualification according to ISO 16750

Manufactured in ISO/TS 16949 certified production sites

Support products

u-blox 6 Evaluation Kits:

Easy-to-use kits to get familiar with u-blox 6 positioning technology, evaluate functionality, and visualize GPS performance.

EVK-6H:	u-blox 6 Evaluation Kit with TCXO, suitable for NEO-6G, NEO-6Q
EVK-6P:	u-blox 6 Evaluation Kit with crystal, suitable for NEO-6M

Ordering information

NEO-6G-0	u-blox 6 GPS Module, 1.8V, TCXO, 12x16mm, 250 pcs/reel
NEO-6M-0	u-blox 6 GPS Module, 12x16mm, 250 pcs/reel
NEO-6Q-0	u-blox 6 GPS Module, TCXO, 12x16mm, 250 pcs/reel

Available as samples and tape on reel (250 pieces)

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